

# **Time-Code Receiver with Digitized Serial Output**

# **Description**

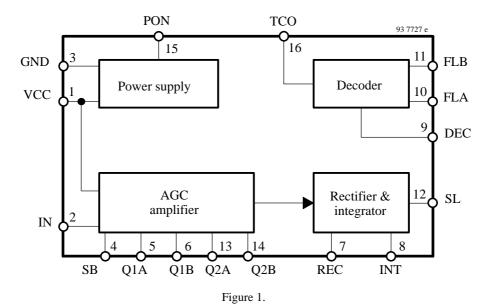
The U4224B is a bipolar integrated straight-through receiver circuit in the frequency range of 40 to 80 kHz. The device is designed for radio-controlled clock applications.

## **Features**

- Very low power consumption
- Very high sensitivity
- High selectivity by using two crystal filters
- Power-down mode available

- Only a few external components necessary
- Digitalized serial output signal
- AGC hold mode

# **Block Diagram**



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# **Pin Description**

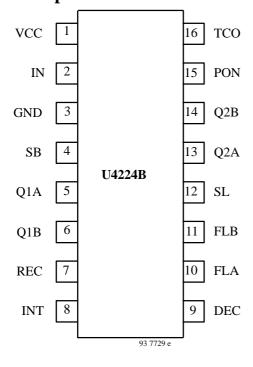


Figure 2. Pinning

Pin	Symbol	Function	
1	VCC	Supply voltage	
2	IN	Amplifier – Input	
3	GND	Ground	
4	SB	Bandwidth control	
5	Q1A	Crystal filter 1	
6	Q1B	Crystal filter 1	
7	REC	Rectifier output	
8	INT	Integrator output	
9	DEC	Decoder input	
10	FLA	Lowpass filter	
11	FLB	Lowpass filter	
12	SL	AGC hold mode	
13	Q2A	Crystal filter 2	
14	Q2B	Crystal filter 2	
15	PON	Power ON/OFF control	
16	TCO	Time-code output	

## IN

A ferrite antenna is connected between IN and VCC. For high sensitivity, the Q factor of the antenna circuit should be as high as possible. Please note that a high Q factor requires temperature compensation of the resonant frequency in most cases. Specifications are valid for Q > 30. An optimal signal-to-noise ratio will be achieved by a resonant resistance of 50 to 200  $k\Omega$ .



A resistor  $R_{SB}$  is connected between SB and GND. It controls the bandwidth of the crystal filters. It is recommended:  $R_{SB}=0~\Omega$  for DCF 77.5 kHz,  $R_{SB}=10~k\Omega$  for 60 kHz WWVB and  $R_{SB}=$  open for JG2AS 40~kHz.

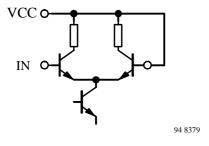


Figure 3.

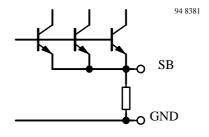


Figure 4.



## **Q1A, Q1B**

In order to achieve a high selectivity, a crystal is connected between the Pins Q1A and Q1B. It is used with the serial resonant frequency of the time-code transmitter (e.g., 60 kHz WWVB, 77.5 kHz DCF or 40 kHz JG2AS).

The equivalent parallel capacitor of the filter crystal is internally compensated. The compensated value is about 0.7 pF. If full sensitivity and selectivity are not needed, the crystal filter can be substituted by a capacitor of 10 pF for DCF and WWVB and 22 pF for JG2AS.

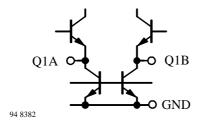


Figure 5.

## **REC**

Rectifier output and integrator input: The capacitor  $C_1$  between REC and INT is the lowpass filter of the rectifier and at the same time a damping element of the gain control.

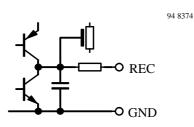


Figure 6.

## **DEC**

Decoder input: Senses the current through the integration capacitor  $C_2$ . The dynamic input resistance has a value of about 420 k $\Omega$  and is low compared to the impedance of  $C_2$ .

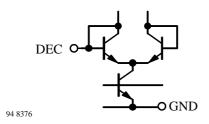
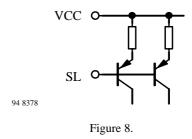


Figure 7.

## SL

AGC hold mode: SL high ( $V_{SL} = V_{CC}$ ) sets normal function, SL low ( $V_{SL} = 0$ ) disconnects the rectifier and holds the voltage  $V_{INT}$  at the integrator output and also the AGC amplifier gain.



## **INT**

Integrator output: The voltage  $V_{INT}$  is the control voltage for the AGC. The capacitor  $C_2$  between INT and DEC defines the time constant of the integrator. The current through the capacitor is the input signal of the decoder.

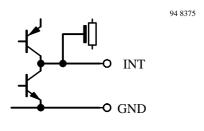
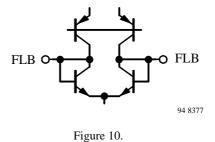


Figure 9.

## FLA, FLB

Lowpass filter: A capacitor C<sub>3</sub> connected between FLA and FLB suppresses higher frequencies at the trigger circuit of the decoder.



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## **Q2A, Q2B**

According to Q1A/Q1B, a crystal is connected between the Pins Q2A and Q2B. It is used with the serial resonant frequency of the time-code transmitter (e.g., 60 kHz WWVB, 77.5 kHz DCF or 40 kHz JG2AS). The equivalent parallel capacitor of the filter crystal is internally compensated. The value of the compensation is about 0.7 pF.

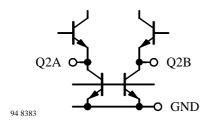


Figure 11.

## **PON**

If PON is connected to GND, the receiver will be activated. The set-up time is typically 0.5 s after applying GND at this pin. If PON is connected to VCC, the receiver will switch to power-down mode.

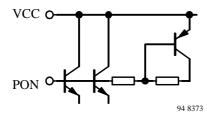
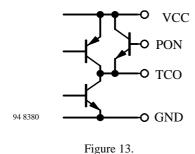


Figure 12.

#### **TCO**

The digitized serial signal of the time-code transmitter can be directly decoded by a microcomputer. Details about the time-code format of several transmitters are described separately.

The output consists of a PNP-NPN push-pull-stage. It should be taken into account that in power-down mode (PON = high), TCO will be high.



An additional improvement of the driving capability may be achieved by using a CMOS driver circuit or an NPN transistor with pull-up resistor connected to the collector (see figure 14). When using a CMOS driver, this circuit must be connected to VCC.

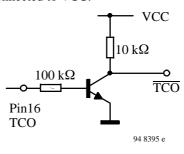


Figure 14.

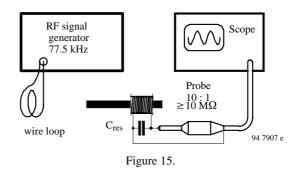
#### Please note:

The signals and voltages at the Pins REC, INT, FLA, FLB, Q1A, Q1B, Q2A and Q2B cannot be measured by standard measurement equipment due to very high internal impedances. For the same reason, the PCB should be protected against surface humidity.

## **Design Hints for the Ferrite Antenna**

The bar antenna is a very critical device of the complete clock receiver. Observing some basic RF design rules helps to avoid possible problems. The IC requires a resonant resistance of  $50~k\Omega$  to  $200~k\Omega$ . This can be achieved by a variation of the L/C-relation in the antenna circuit. It is not easy to measure such high resistances in the RF region. A more convenient way is to distinguish between the different bandwidths of the antenna circuit and to calculate the resonant resistance afterwards.

Thus, the first step in designing the antenna circuit is to measure the bandwidth. Figure 16 shows an example for the test circuit. The RF signal is coupled into the bar antenna by inductive means, e.g., a wire loop. It can be measured by a simple oscilloscope using the 10:1 probe. The input capacitance of the probe, typically about 10 pF, should be taken into consideration. By varying the frequency of the signal generator, the resonant frequency can be determined.



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At the point where the voltage of the RF signal at the probe drops by 3 dB, the two frequencies can then be measured. The difference between these two frequencies is called the bandwidth  $BW_A$  of the antenna circuit. As the value of the capacitor  $C_{res}$  in the antenna circuit is known, it is easy to compute the resonant resistance according to the following formula:

$$R_{res} = \frac{1}{2 \, \times \, \pi \, \times BW_A \times \, C_{res}}$$

where

 $R_{res}$  is the resonant resistance,  $BW_A$  is the measured bandwidth (in Hz),  $C_{res}$  is the value of the capacitor in the antenna circuit (in Farad).

If high inductance values and low capacitor values are used, the additional parasitic capacitances of the coil ( $\leq$ 20 pF) must be considered. The Q value of the capacitor should be no problem if a high Q type is used. The Q value of the coil differs more or less from the DC resistance of the wire. Skin effects can be observed but do not dominate.

Therefore, it should not be a problem to achieve the recommended values of the resonant resistance. The use of thicker wire increases the Q value and accordingly reduces bandwidth. This is advantageous in order to improve reception in noisy areas. On the other hand, temperature compensation of the resonant frequency might become a problem if the bandwidth of the antenna

circuit is low compared to the temperature variation of the resonant frequency. Of course, the Q value can also be reduced by a parallel resistor.

Temperature compensation of the resonant frequency is a must if the clock is used at different temperatures. Please ask your supplier of bar antenna material and of capacitors for specified values of the temperature coefficient.

Furthermore, some critical parasitics have to be considered. These are shortened loops (e.g., in the ground line of the PCB board) close to the antenna and undesired loops in the antenna circuit. Shortened loops decrease the Q value of the circuit. They have the same effect like conducting plates close to the antenna. To avoid undesired loops in the antenna circuit, it is recommended to mount the capacitor  $C_{\text{res}}$  as close as possible to the antenna coil or to use a twisted wire for the antenna-coil connection. This twisted line is also necessary to reduce feedback of noise from the microprocessor to the IC input. Long connection lines must be shielded.

A final adjustment of the time-code receiver can be carried out by pushing the coil along the bar antenna. The maximum of the integrator output voltage  $V_{INT}$  at Pin INT indicates the resonant point. But attention: The load current should not exceed 1 nA, that means an input resistance  $\geq 1~G\Omega$  of the measuring device is required. Therefore, a special DVM or an isolation amplifier is necessary.

## **Absolute Maximum Ratings**

Parameters	Symbol	Value	Unit
Supply voltage	V <sub>CC</sub>	5.25	V
Ambient temperature range	T <sub>amb</sub>	-25 to +75	°C
Storage temperature range	R <sub>stg</sub>	-40 to +85	°C
Junction temperature	T <sub>j</sub>	125	°C
Electrostatic handling (MIL Standard 883 D), except Pins 5, 6, 13 and 14	± V <sub>ESD</sub>	2000	V

## **Thermal Resistance**

Parameters	Symbol	Value	Unit
Thermal resistance	$R_{thJA}$	70	K/W

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# **Electrical Characteristics**

 $V_{CC}$  = 3 V, reference point Pin 3, input signal frequency 80 kHz,  $T_{amb}$  = 25 °C, unless otherwise specified

Parameters	Test Conditions / Pin	Symbol	Min.	Тур.	Max.	Unit
Supply voltage range	Pin 1	V <sub>CC</sub>	1.2		5.25	V
Supply current	Pin 1	I <sub>CC</sub>				
	Without reception signal				30	μA
	with reception signal = $200 \mu\text{V}$			15	25	μΑ
	OFF mode			2	0.1	μΑ
Set-up time after V <sub>CC</sub> ON	$V_{CC} = 1.5 \text{ V}$	t		2		S
1 /	Pin 2	1 0	40		1 00	
Reception frequency range		f <sub>in</sub>	40		80	kHz
Minimum input voltage	$R_{res} = 100 \text{ k}\Omega, \ Q_{res} > 30$	V <sub>in</sub>		1	1.5	μV
Maximum input voltage		V <sub>in</sub>	40	80		mV
Input capacitance to ground		C <sub>in</sub>		1.5		pF
Timing code output; TCO	Pin 16					
Output voltage						
HIGH	$R_{LOAD} = 870 \text{ k}\Omega \text{ to GND}$	V <sub>OH</sub>	$V_{CC}$ -0.4			V
LOW	$R_{LOAD} = 650 \text{ k}\Omega \text{ to VCC}$	V <sub>OL</sub>			0.4	V
Output current HIGH	V = V /2	T	3	10		
LOW	$\begin{vmatrix} V_{TCO} = V_{CC}/2 \\ V_{TCO} = V_{CC}/2 \end{vmatrix}$	I <sub>SOURCE</sub> I <sub>SINK</sub>	3 4	12		μΑ μΑ
Decoding characteristics	DCF77 based on the values of	ISINK		12		μιτ
Decoding characteristics	the application circuit fig. 17					
	TCO pulse width 100 ms	t <sub>100</sub>	60	90	130	ms
	TCO pulse width 200 ms	t <sub>200</sub>	160	190	230	ms
	Delay compared with the					
	transient of the RF signal:					
	drop down (start transition)	$t_s$	30		60	ms
	rise for 100 ms pulse	t <sub>e1</sub>	25		55	ms
	(end transition)					
	rise for 200 ms pulse	t <sub>e2</sub>	10		30	ms
	(end transition)					
Decoding characteristics	WWVB based on the values of					
	the application circuit fig. 18 TCO pulse width 200 ms	t	140		200	ma
	TCO pulse width 500 ms	t <sub>200</sub> t <sub>500</sub>	440		500	ms ms
	TCO pulse width 800 ms	t <sub>800</sub>	740		800	ms
	F	-500				
	Delay compared with the					
	transient of the RF signal:					
	duon doven (stant tuonaiti ===)		15		90	
	drop down (start transition) rise (end transition)	t <sub>s</sub>	45 20		80 45	ms ms
	115C (CHG transition)	t <sub>e</sub>	20		43	1115



# **Electrical Characteristics**

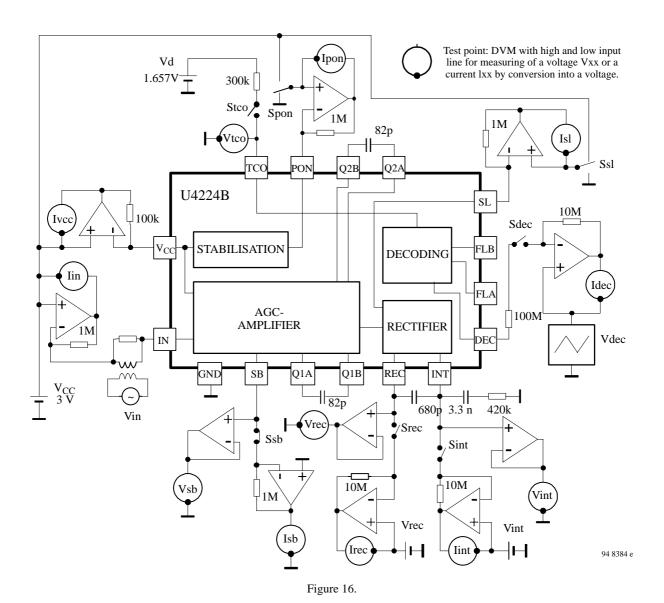
 $V_{CC} = 3$  V, reference point Pin 3, input signal frequency 80 kHz,  $T_{amb} = 25$  °C, unless otherwise specified

Parameters	Test Conditions / Pin	Symbol	Min.	Тур.	Max.	Unit	
Decoding characteristics	JG2AS based on the values of the application circuit fig. 19: TCO pulse width 200 ms TCO pulse width 500 ms TCO pulse width 800 ms Delay compared with the transient of the RF signal:	t <sub>200</sub> t <sub>500</sub> t <sub>800</sub>	240 420 720		410 490 790	ms ms ms	
	start transition (RF on) end transition (RF off)	t <sub>s</sub> t <sub>e</sub>	10 30		110 220	ms ms	
Power-ON/OFF control; PO	Power-ON/OFF control; PON Pin 15						
Input voltage HIGH LOW	Required $I_{IN} \ge 0.5 \mu A$		V <sub>CC</sub> -0.2		V <sub>CC</sub> -1.2	V V	
Input current	$V_{CC} = 3V$ $V_{CC} = 1.5 V$ $V_{CC} = 5 V$	I <sub>IN</sub>	1.4	1.7 0.7 3	V <sub>CC</sub> -1.2	μΑ μΑ μΑ	
Set-up time after PON		t		0.5	2	s	
AGC hold mode; SL Pin 12							
Input voltage HIGH LOW	Required $I_{IN} \ge 0.5 \mu A$		V <sub>CC</sub> -0.2		V <sub>CC</sub> -1.2	V V	
Input current	$\begin{aligned} V_{in} &= V_{CC} \\ V_{in} &= GND \end{aligned}$			2.5	0.1	μ <b>Α</b> μ <b>Α</b>	
Rejection of interference signals	$\begin{array}{c c} \left  f_d - f_{ud} \right  = 625 \; Hz \\ V_d = 3 \; \mu V, \; f_d = 77.5 \; kHz \\ using \; 2 \; crystal \; filters \\ using \; 1 \; crystal \; filter \end{array}$	a <sub>f</sub> a <sub>f</sub>		43 22		dB dB	

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# **Test Circuit (for Fundamental Function)**



# **Application Circuit for DCF 77.5 kHz**

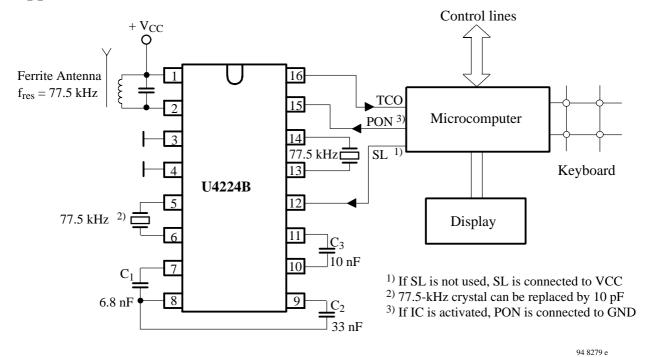


Figure 17.

# Application Circuit for WWVB 60 kHz

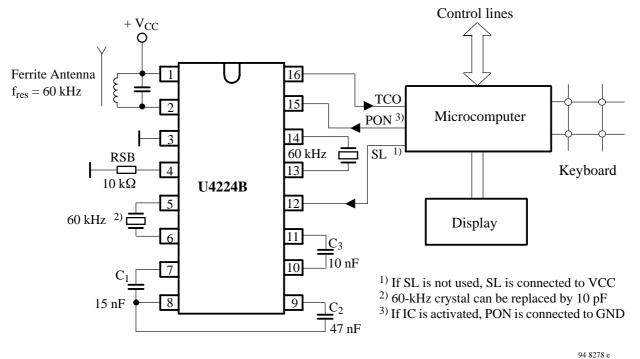


Figure 18.



# **Application Circuit for JG2AS 40 kHz**

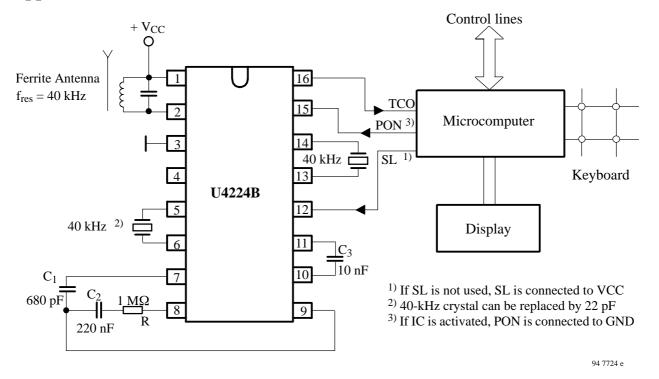


Figure 19.



## **Information on the German Transmitter**

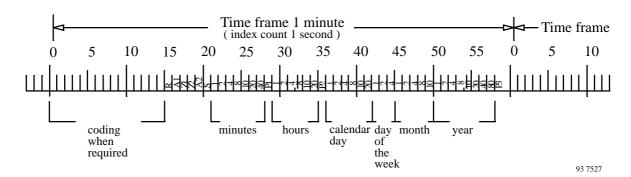
Station: DCF 77, Frequency 77.5 kHz,

Transmitting power 50 kW

Location: Mainflingen/Germany,

Geographical coordinates: 50°° 0.1'N, 09°° 00'E

Time of transmission: permanent



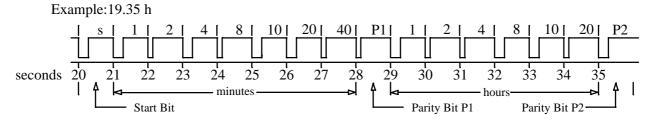


Figure 20.

## **Modulation**

The carrier amplitude is reduced to 25% at the beginning of each second for a period of 100 ms (binary zero) or 200 ms (binary one), except the 59th second.

# Time-Code Format (based on Information of Deutsche Bundespost)

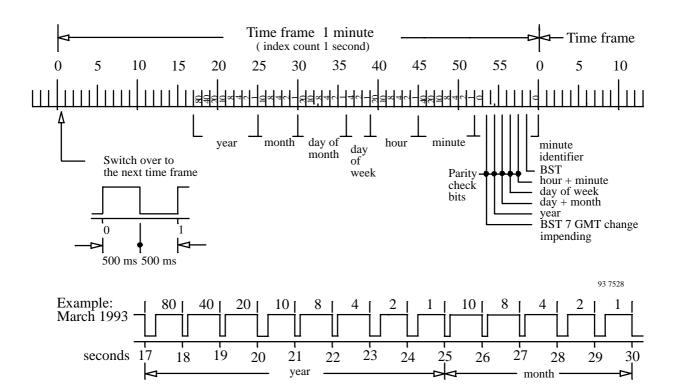
The time-code format consists of 1-minute time frames. There is no modulation at the beginning of the 59th

second to indicate the switch over to the next 1-minute time frame. A time frame contains BCD-coded information of minutes, hours, calendar day, day of the week, month and year between the 20th second and 58th second of the time frame, including the start bit S (200 ms) and parity bits P1, P2 and P3. Furthermore, there are 5 additional bits R (transmission by reserve antenna), A1 (announcement of change-over to summer time), Z1 (during summer time 200 ms, otherwise 100 ms), Z2 (during standard time 200 ms, otherwise 100 ms) and A2 (announcement of leap second) transmitted between the 15th second and 19th second of the time frame.



## **Information on the British Transmitter**

Station: MSF Frequency 60 kHz Transmitting power 50 kW Location: Teddington, Middlesex Geographical coordinates:  $52^{\circ\circ}$  22'N,  $01^{\circ}$  11'W Time of transmission: permanent, except the first Tuesday of each month from 10.00 h to 14.00 h.



## Figure 21.

## **Modulation**

The carrier amplitude is switched off at the beginning of each second for a period of 100 ms (binary zero) or 200 ms (binary one).

## **Time-Code Format**

The time-code format consists of 1-minute time frames. A time frame contains BCD-coded information of year, month, calendar day, day of the week, hours and minutes. At the switch-over to the next time frame, the carrier amplitude is reduced for a period of 500 ms.

The prescence of the fast code during the first 500 ms at the beginning of the minute in not guaranteed. The transmission rate is 100 bits/s and the code contains information of hour, minute, day and month.

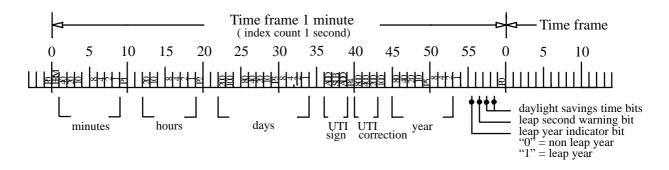


## **Information on the US Transmitter**

Station: WWVB Frequency 60 kHz Transmitting power 10 kW Location: Fort Collins

Geographical coordinates: 40°° 40'N, 105°° 03'W

Time of transmission: permanent



93 7529 e

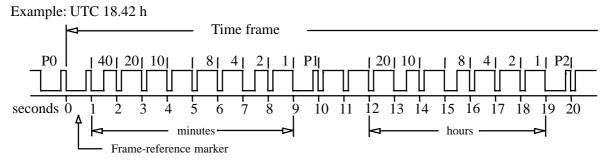


Figure 22.

## **Modulation**

The carrier amplitude is reduced by 10 dB at the beginning of each second and is restored within 500 ms (binary one) or within 200 ms (binary zero).

## **Time-Code Format**

The time-code format consists of 1-minute time frames. A time frame contains BCD1-coded information of minutes, hours, days and year. In addition, there are 6 position-identifier markers (P0 thru P5) and 1 frame-reference marker with reduced carrier amplitude of 800 ms duration.



## Information on the Japanese Transmitter

Station: JG2AS

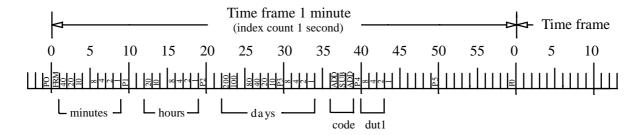
Frequency 40 kHz

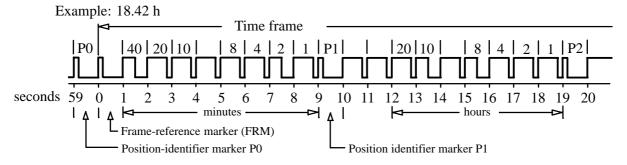
Transmitting power 10 kW

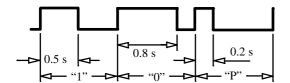
Location: Sanwa, Ibaraki

Geographical coordinates: 36° 11' N, 139° 51' E

Time of transmission: permanent







- 0.5 second: Binary one
- 0.8 second: Binary zero

0.2 second: Identifier markers P0...P5

93 7508 e

Figure 23.

## **Modulation**

The carrier amplitude is 100% at the beginning of each second and is switched off after 500 ms (binary one) or after 800 ms (binary zero).

## **Time-Code Format**

The time-code format consists of 1-minute time frames. A time frame contains BCD-coded information of minutes, hours and days. In addition, there are 6 position-identifier markers (P0 thru P5) and 1 frame-reference marker (FRM) with reduced carrier amplitude of 800 ms duration.

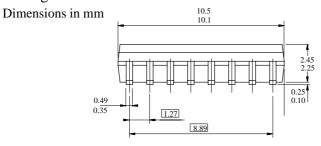
# **Ordering and Package Information**

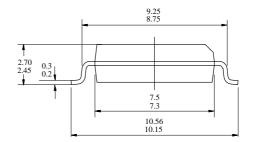
Extended Type Number	Package	Remarks
U4224B-CFL	SO16L plastic	
U4224B-CFLG3	SO16L plastic	Taping according to IEC-286-3

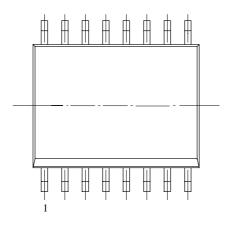


# **Package Information**

# Package SO16L









95 11493



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It is the policy of **TEMIC Semiconductor GmbH** to

- 1. Meet all present and future national and international statutory requirements.
- 2. Regularly and continuously improve the performance of our products, processes, distribution and operating systems with respect to their impact on the health and safety of our employees and the public, as well as their impact on the environment.

It is particular concern to control or eliminate releases of those substances into the atmosphere which are known as ozone depleting substances (ODSs).

The Montreal Protocol (1987) and its London Amendments (1990) intend to severely restrict the use of ODSs and forbid their use within the next ten years. Various national and international initiatives are pressing for an earlier ban on these substances.

**TEMIC Semiconductor GmbH** has been able to use its policy of continuous improvements to eliminate the use of ODSs listed in the following documents.

- 1. Annex A, B and list of transitional substances of the Montreal Protocol and the London Amendments respectively
- 2. Class I and II ozone depleting substances in the Clean Air Act Amendments of 1990 by the Environmental Protection Agency (EPA) in the USA
- 3. Council Decision 88/540/EEC and 91/690/EEC Annex A, B and C (transitional substances) respectively.

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